## feATURES

- 100MHz Gain Bandwidth
- 750V/us Slew Rate
- 3.6mA Maximum Supply Current
- 50uA Supply Current in Shutdown
- $8 \mathrm{nV} / \sqrt{H z}$ Input Noise Voltage
- Unity-Gain Stable
- 1.5mV Maximum Input Offset Voltage
- $4 \mu \mathrm{~A}$ Maximum Input Bias Current
- 400nA Maximum Input Offset Current
- 40mA Minimum Output Current, $\mathrm{V}_{\text {OUT }}= \pm 3 \mathrm{~V}$
- $\pm 3.5 \mathrm{~V}$ Minimum Input CMR, $\mathrm{V}_{\mathrm{S}}= \pm 5 \mathrm{~V}$
- 30ns Settling Time to 0.1\%, 5V Step
- Specified at $\pm 5 \mathrm{~V}$, Single 5V Supplies
- Operating Temperature Range: $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$


## APPLICATIONS

- Wideband Amplifiers
- Buffers
- Active Filters
- Video and RF Amplification
- Cable Drivers
- Data Acquisition Systems


## DESCRIPTIOn

The $\mathrm{LT}^{\circledR} 1812$ is a low power, high speed, very high slew rate operational amplifier with excellent DC performance. The LT1812 features reduced supply current, lower input offset voltage, lower input bias current and higher DC gain than other devices with comparable bandwidth. A power saving shutdown feature reduces supply current to $50 \mu \mathrm{~A}$. The circuit topology is a voltage feedback amplifier with the slewing characteristics of a current feedback amplifier.
The output drives a $100 \Omega$ load to $\pm 3.5 \mathrm{~V}$ with $\pm 5 \mathrm{~V}$ supplies. On a single 5 V supply, the output swings from 1.1 V to 3.9 V with a $100 \Omega$ load connected to 2.5 V . The amplifier is stable with a 1000 pF capacitive load which makes it useful in buffer and cable driver applications.
The LT1812 is manufactured on Linear Technology's advanced low voltage complementary bipolar process. The dual version is the LT1813. For higher supply voltage single, dual and quad operational amplifiers with up to 70MHz gain bandwidth, see the LT1351 through LT1365 data sheets.
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## TYPICAL APPLICATION

4MHz, 4th Order Butterworth Filter


Filter Frequency Response


## ABSOLUTE MAXIMUM RATINGS

(Note 1)
Total Supply Voltage ( $\mathrm{V}^{+}$to $\mathrm{V}^{-}$)............................. 12.6V
Differential Input Voltage (Transient Only, Note 2) ... $\pm 3 \mathrm{~V}$
Input Voltage $\qquad$
Output Short-Circuit Duration (Note 3) ............ Indefinite Operating Temperature Range (Note 8) ... $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ Specified Temperature Range (Note 8) $\qquad$ $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$
Maximum Junction Temperature ......................... $150^{\circ} \mathrm{C}$ Storage Temperature Range .................. $-65^{\circ} \mathrm{C}$ to $150^{\circ} \mathrm{C}$ Lead Temperature (Soldering, 10 sec ) $300^{\circ} \mathrm{C}$

PACKAGE/ORDER INFORMATION

| TOP VIEW | ORDER PART NUMBER |
| :---: | :---: |
|  | $\begin{aligned} & \text { LT1812CS8 } \\ & \text { LT1812IS8 } \end{aligned}$ |
| $\mathrm{V}^{-4} \square 5 \mathrm{5C}$ | S8 PART MARKING |
| 8-LLEAD PLASTIC SO | 1812 |
| $\mathrm{T}_{\text {Max }}=150^{\circ} \mathrm{C}, \theta_{\mathrm{JA}}=80^{\circ} \mathrm{C} / \mathrm{W}$ ( (NOTE 9) | 18121 |

Consult factory for Military grade parts.

## ELECTRICAL CHARACTERISTICS <br> $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{S}}= \pm 5 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=\mathrm{OV}$ unless otherwise noted.

| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {OS }}$ | Input Offset Voltage | (Note 4) |  | 0.4 | 1.5 | mV |
| Ios | Input Offset Current |  |  | 30 | 400 | nA |
| $\mathrm{I}_{\mathrm{B}}$ | Input Bias Current |  |  | -0.9 | $\pm 4$ | $\mu \mathrm{A}$ |
| $\mathrm{e}_{\mathrm{n}}$ | Input Noise Voltage Density | $\mathrm{f}=10 \mathrm{kHz}$ |  | 8 |  | $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ |
| $\mathrm{i}_{n}$ | Input Noise Current Density | $\mathrm{f}=10 \mathrm{kHz}$ |  | 1 |  | $\mathrm{pA} / \sqrt{ } \mathrm{Hz}$ |
| $\mathrm{R}_{\text {IN }}$ | Input Resistance | $\begin{aligned} & \mathrm{V}_{\mathrm{CM}}= \pm 3.5 \mathrm{~V} \\ & \text { Differential } \end{aligned}$ | 3 | $\begin{aligned} & 10 \\ & 1.5 \end{aligned}$ |  | $\mathrm{M} \Omega$ $\mathrm{M} \Omega$ |
| $\mathrm{C}_{\text {IN }}$ | Input Capacitance |  |  | 2 |  | pF |
| $\mathrm{V}_{\text {CM }}$ | Input Voltage Range (Positive) Input Voltage Range (Negative) |  | 3.5 | $\begin{array}{r} 4.2 \\ -4.2 \end{array}$ | -3.5 | V |
| CMRR | Common Mode Rejection Ratio | $\mathrm{V}_{\text {CM }}= \pm 3.5 \mathrm{~V}$ | 75 | 85 |  | dB |
|  | Minimum Supply Voltage |  |  | $\pm 1.25$ | $\pm 2$ | V |
| PSRR | Power Supply Rejection Ratio | $\mathrm{V}_{S}= \pm 2 \mathrm{~V}$ to $\pm 5.5 \mathrm{~V}$ | 78 | 97 |  | dB |
| AVOL | Large-Signal Voltage Gain | $\begin{aligned} & V_{\text {OUT }}= \pm 3 V, R_{L}=500 \Omega \\ & V_{\text {OUT }}= \pm 3 V, R_{L}=100 \Omega \end{aligned}$ | $\begin{aligned} & 1.5 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 3.0 \\ & 2.5 \end{aligned}$ |  | $\mathrm{V} / \mathrm{mV}$ $\mathrm{V} / \mathrm{mV}$ |
| $\mathrm{V}_{\text {OUT }}$ | Maximum Output Swing | $\begin{aligned} & \mathrm{R}_{\mathrm{L}}=500 \Omega, 30 \mathrm{mV} \text { Overdrive } \\ & \mathrm{R}_{\mathrm{L}}=100 \Omega, 30 \mathrm{mV} \text { Overdrive } \\ & \hline \end{aligned}$ | $\begin{aligned} & \pm 3.80 \\ & \pm 3.35 \end{aligned}$ | $\begin{aligned} & \pm 4.0 \\ & \pm 3.5 \end{aligned}$ |  | V |
| IOUT | Maximum Output Current | $\mathrm{V}_{\text {OUT }}= \pm 3 \mathrm{~V}, 30 \mathrm{mV}$ Overdrive | $\pm 40$ | $\pm 60$ |  | mA |
| ISC | Output Short-Circuit Current | $\mathrm{V}_{\text {OUT }}=0 \mathrm{~V}$, 1V Overdrive (Note 3) | $\pm 75$ | $\pm 110$ |  | mA |
| SR | Slew Rate | $A_{V}=-1$ (Note 5) | 500 | 750 |  | $\mathrm{V} / \mathrm{\mu s}$ |
| FPBW | Full Power Bandwidth | 3V Peak (Note 6) |  | 40 |  | MHz |
| GBW | Gain Bandwidth Product | $\mathrm{f}=200 \mathrm{kHz}$ | 75 | 100 |  | MHz |
| $\mathrm{tr}_{\mathrm{r}}, \mathrm{t}_{\mathrm{f}}$ | Rise Time, Fall Time | $A_{V}=1,10 \%$ to $90 \%, 0.1 V, R_{L}=100 \Omega$ |  | 2 |  | ns |
| OS | Overshoot | $A_{V}=1,0.1 \mathrm{~V}, \mathrm{R}_{L}=100 \Omega$ |  | 25 |  | \% |
| tPD | Propagation Delay | $A_{V}=1,50 \% V_{\text {IN }}$ to $50 \% V_{\text {OUT }}, 0.1 \mathrm{~V}, \mathrm{R}_{L}=100 \Omega$ |  | 2.8 |  | ns |
| $\mathrm{t}_{\text {s }}$ | Settling Time | 5 V Step, $0.1 \%, \mathrm{~A}_{V}=-1$ |  | 30 |  | ns |
| THD | Total Harmonic Distortion | $f=1 \mathrm{MHz}, \mathrm{V}_{\text {OUT }}=2 V_{\text {P-P }}, A_{V}=2, R_{L}=500 \Omega$ |  | -76 |  | dB |
|  | Differential Gain | $V_{\text {OUT }}=2 V_{\text {P-P }}, A_{V}=2, R_{L}=150 \Omega$ |  | 0.12 |  | \% |
|  | Differential Phase | $V_{\text {OUT }}=2 V_{\text {P-P }}, A_{V}=2, R_{L}=150 \Omega$ |  | 0.07 |  | DEG |
| R ${ }_{\text {OUT }}$ | Output Resistance | $A_{V}=1, \mathrm{f}=1 \mathrm{MHz}$ |  | 0.4 |  | $\Omega$ |

## ELECTRICAL CHARACTERISTICS $T_{A}=25^{\circ}, V_{S}= \pm 5 v, v_{c m}=0 V$ unless otherwise noted.

| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ISHDN | $\overline{\text { SHDN }}$ Pin Current | $\begin{aligned} & \overline{\mathrm{SHDN}}>\mathrm{V}^{-}+2.0 \mathrm{~V}(0 \mathrm{On}) \\ & \overline{\text { SHDN }}<\mathrm{V}^{-}+0.4 \mathrm{~V}(0 \mathrm{ff}) \end{aligned}$ | -100 | $\begin{gathered} 0 \\ -50 \end{gathered}$ | $\pm 1$ | $\mu \mathrm{A}$ $\mu \mathrm{A}$ |
| IS | Supply Current | $\begin{aligned} & \overline{\mathrm{SHDN}}>\mathrm{V}^{-}+2.0 \mathrm{~V}(0 \mathrm{On}) \\ & \overline{\text { SHDN }}<\mathrm{V}^{-}+0.4 \mathrm{~V}(0 \mathrm{ff}) \end{aligned}$ |  | $\begin{gathered} 3 \\ 50 \end{gathered}$ | $\begin{aligned} & 3.6 \\ & 100 \end{aligned}$ | mA $\mu \mathrm{A}$ |

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{S}}=5 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=2.5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}$ to 2.5 V unless otherwise noted.

| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {OS }}$ | Input Offset Voltage | (Note 4) |  | 0.5 | 2.0 | mV |
| Ios | Input Offset Current |  |  | 30 | 400 | nA |
| $\mathrm{I}_{\mathrm{B}}$ | Input Bias Current |  |  | -1.0 | $\pm 4$ | $\mu \mathrm{A}$ |
| $\mathrm{e}_{\mathrm{n}}$ | Input Noise Voltage Density | $f=10 \mathrm{kHz}$ |  | 8 |  | $\mathrm{nV} / \sqrt{\mathrm{Hz}}$ |
| $\mathrm{in}_{n}$ | Input Noise Current Density | $\mathrm{f}=10 \mathrm{kHz}$ |  | 1 |  | $\mathrm{pA} / \sqrt{\mathrm{Hz}}$ |
| $\mathrm{R}_{\text {IN }}$ | Input Resistance | $\begin{aligned} & \mathrm{V}_{C M}=1.5 \mathrm{~V} \text { to } 3.5 \mathrm{~V} \\ & \text { Differential } \end{aligned}$ | 3 | $\begin{aligned} & \hline 10 \\ & 1.5 \end{aligned}$ |  | $\begin{aligned} & \mathrm{M} \Omega \\ & \mathrm{M} \Omega \end{aligned}$ |
| $\overline{C_{\text {IN }}}$ | Input Capacitance |  |  | 2 |  | pF |
| $\mathrm{V}_{\text {CM }}$ | Input Voltage Range (Positive) Input Voltage Range (Negative) |  | 3.5 | $\begin{aligned} & 4 \\ & 1 \end{aligned}$ | 1.5 | V |
| CMRR | Common Mode Rejection Ratio | $\mathrm{V}_{\text {CM }}=1.5 \mathrm{~V}$ to 3.5 V | 73 | 82 |  | dB |
| AVOL | Large-Signal Voltage Gain | $\begin{aligned} & \mathrm{V}_{\text {OUT }}=1.5 \mathrm{~V} \text { to } 3.5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=500 \Omega \\ & \mathrm{~V}_{\text {OUT }}=1.5 \mathrm{~V} \text { to } 3.5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=100 \Omega \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 0.7 \end{aligned}$ | $\begin{aligned} & 2.0 \\ & 1.5 \end{aligned}$ |  | $\begin{aligned} & \mathrm{V} / \mathrm{mV} \\ & \mathrm{~V} / \mathrm{mV} \end{aligned}$ |
| $\overline{V_{\text {OUT }}}$ | Maximum Output Swing (Positive) | $\begin{array}{\|l} \hline \mathrm{R}_{\mathrm{L}}=500 \Omega, 30 \mathrm{mV} \text { Overdrive } \\ \mathrm{R}_{\mathrm{L}}=100 \Omega, 30 \mathrm{mV} \text { Overdrive } \\ \hline \end{array}$ | $\begin{aligned} & 3.9 \\ & 3.7 \end{aligned}$ | $\begin{aligned} & 4.1 \\ & 3.9 \end{aligned}$ |  | V |
|  | Maximum Output Swing (Negative) | $\begin{array}{\|l} \hline \mathrm{R}_{\mathrm{L}}=500 \Omega, 30 \mathrm{mV} \text { Overdrive } \\ \mathrm{R}_{\mathrm{L}}=100 \Omega, 30 \mathrm{mV} \text { Overdrive } \\ \hline \end{array}$ |  | $\begin{aligned} & 0.9 \\ & 1.1 \end{aligned}$ | $\begin{aligned} & 1.1 \\ & 1.3 \end{aligned}$ | V |
| IOUT | Maximum Output Current | $\mathrm{V}_{\text {OUT }}=3.5 \mathrm{~V}$ or $1.5 \mathrm{~V}, 30 \mathrm{mV}$ Overdrive | $\pm 25$ | $\pm 40$ |  | mA |
| ISC | Output Short-Circuit Current | $\mathrm{V}_{\text {OUT }}=2.5 \mathrm{~V}$, 1V Overdrive (Note 3) | $\pm 55$ | $\pm 80$ |  | mA |
| SR | Slew Rate | $A_{V}=-1$ (Note 5) | 200 | 350 |  | V/ $/ \mathrm{S}$ |
| FPBW | Full Power Bandwidth | 1V Peak (Note 6) |  | 55 |  | MHz |
| GBW | Gain Bandwidth Product | $\mathrm{f}=200 \mathrm{kHz}$ | 65 | 94 |  | MHz |
| $\mathrm{t}_{\mathrm{r}, \mathrm{t}_{\mathrm{f}}}$ | Rise Time, Fall Time | $A_{V}=1,10 \%$ to $90 \%, 0.1 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=100 \Omega$ |  | 2.1 |  | ns |
| OS | Overshoot | $A_{V}=1,0.1 \mathrm{~V}, \mathrm{R}_{L}=100 \Omega$ |  | 25 |  | \% |
| tPD | Propagation Delay | $A_{V}=1,50 \% \mathrm{~V}_{\text {IN }}$ to $50 \% \mathrm{~V}_{\text {OUT }}, 0.1 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=100 \Omega$ |  | 3 |  | ns |
| $\mathrm{t}_{\text {s }}$ | Settling Time | 2V Step, 0.1\%, $\mathrm{A}_{V}=-1$ |  | 30 |  | ns |
| THD | Total Harmonic Distortion | $f=1 \mathrm{MHz}, \mathrm{V}_{\text {OUT }}=2 V_{\text {P-P }}, A_{V}=2, R_{L}=500 \Omega$ |  | -75 |  | dB |
|  | Differential Gain | $V_{\text {OUT }}=2 V_{\text {P-P }}, A_{V}=2, R_{L}=150 \Omega$ |  | 0.22 |  | \% |
|  | Differential Phase | $V_{\text {OUT }}=2 V_{\text {P-P }}, A_{V}=2, \mathrm{R}_{L}=150 \Omega$ |  | 0.21 |  | DEG |
| Rout | Output Resistance | $A_{V}=1, f=1 \mathrm{MHz}$ |  | 0.45 |  | $\Omega$ |
| $\overline{\text { SHDN }}$ | SHDN Pin Current | $\begin{aligned} & \overline{\mathrm{SHDN}}>\mathrm{V}^{-}+2.0 \mathrm{~V}(0 \mathrm{On}) \\ & \overline{\mathrm{SHDN}}<\mathrm{V}^{-}+0.4 \mathrm{~V}(0 \mathrm{ff}) \end{aligned}$ | -50 | $\begin{gathered} 0 \\ -20 \end{gathered}$ | $\pm 1$ | $\mu \mathrm{A}$ $\mu \mathrm{A}$ |
| $\mathrm{I}_{S}$ | Supply Current | $\begin{aligned} & \hline \overline{\mathrm{SHDN}}>\mathrm{V}^{-}+2.0 \mathrm{~V}(0 \mathrm{n}) \\ & \overline{\text { SHDN }}<\mathrm{V}^{-}+0.4 \mathrm{~V}(0 \mathrm{ff}) \end{aligned}$ |  | $\begin{aligned} & 2.7 \\ & 20 \end{aligned}$ | $\begin{aligned} & 3.6 \\ & 50 \end{aligned}$ | mA $\mu \mathrm{A}$ |

$0^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq 70^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{S}}= \pm 5 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=0 \mathrm{~V}$ unless otherwise noted.

| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP | MAX |
| :--- | :--- | :--- | :---: | :---: | :---: |
| $V_{O S}$ | Input Offset Voltage | (Note 4) | 2 | mV |  |
| $\Delta V_{O S} / \Delta T$ | Input Offset Voltage Drift | (Note 7) | 10 | 15 | $\mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ |
| $I_{\text {OS }}$ | Input Offset Current |  | 500 | nA |  |
| $I_{B}$ | Input Bias Current |  | $\pm 5$ | $\mu \mathrm{AA}$ |  |



| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {CM }}$ | Input Voltage Range (Positive) Input Voltage Range (Negative) |  | 3.5 | -3.5 | V |
| CMRR | Common Mode Rejection Ratio | $\mathrm{V}_{\mathrm{CM}}= \pm 3.5 \mathrm{~V}$ | 73 |  | dB |
|  | Minimum Supply Voltage |  |  | $\pm 2$ | V |
| PSRR | Power Supply Rejection Ratio | $\mathrm{V}_{S}= \pm 2 \mathrm{~V}$ to $\pm 5.5 \mathrm{~V}$ | 76 |  | dB |
| AVOL | Large-Signal Voltage Gain | $\begin{aligned} & V_{\text {OUT }}= \pm 3 V, R_{L}=500 \Omega \\ & V_{\text {OUT }}= \pm 3 V, R_{L}=100 \Omega \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 0.7 \end{aligned}$ |  | $\mathrm{V} / \mathrm{mV}$ <br> $\mathrm{V} / \mathrm{mV}$ |
| V OUT | Maximum Output Swing | $\mathrm{R}_{\mathrm{L}}=500 \Omega, 30 \mathrm{mV}$ Overdrive $R_{L}=100 \Omega, 30 \mathrm{mV}$ Overdrive | $\begin{aligned} & \pm 3.70 \\ & \pm 3.25 \end{aligned}$ |  | V |
| IOUT | Maximum Output Current | $\mathrm{V}_{\text {OUT }}= \pm 3 \mathrm{~V}, 30 \mathrm{mV}$ Overdrive | $\pm 35$ |  | mA |
| ISC | Output Short-Circuit Current | $\mathrm{V}_{\text {Out }}=0 \mathrm{~V}$, 1V Overdrive (Note 3) | $\pm 60$ |  | mA |
| SR | Slew Rate | $\mathrm{A}_{V}=-1$ (Note 5) | 400 |  | $\mathrm{V} / \mathrm{\mu S}$ |
| GBW | Gain Bandwidth Product | $\mathrm{f}=200 \mathrm{kHz}$ | 65 |  | MHz |
| $\overline{\text { SHDN }}$ | SHDN Pin Current | $\begin{aligned} & \overline{\mathrm{SHDN}}>\mathrm{V}^{-}+2.0 \mathrm{~V}(0 \mathrm{On}) \\ & \overline{\mathrm{SHDN}}<\mathrm{V}^{-}+0.4 \mathrm{~V}(0 \mathrm{ff}) \end{aligned}$ | -150 | $\pm 1.5$ | $\mu \mathrm{A}$ $\mu \mathrm{A}$ |
| $\mathrm{I}_{S}$ | Supply Current | $\begin{aligned} & \overline{\overline{S H D N}}>\mathrm{V}^{-}+2.0 \mathrm{~V}(0 \mathrm{On}) \\ & \overline{\text { SHDN }}<\mathrm{V}^{-}+0.4 \mathrm{~V}(0 \mathrm{ff}) \end{aligned}$ |  | $\begin{aligned} & 4.6 \\ & 150 \end{aligned}$ | mA $\mu \mathrm{A}$ |

$0^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq 70^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{S}}=5 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=2.5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}$ to 2.5 V unless otherwise noted.

$-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq 85^{\circ} \mathrm{C} . \mathrm{V}_{S}= \pm 5 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=0 \mathrm{~V}$ unless otherwise noted (Note 8).

| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{0 S}$ | Input Offset Voltage | (Note 4) |  |  | 3 | mV |
| $\Delta \mathrm{V}_{\mathrm{OS}} / \Delta \mathrm{T}$ | Input Offset Voltage Drift | (Note 7) |  | 10 | 30 | $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ |
| $\mathrm{I}_{\text {OS }}$ | Input Offset Current |  |  |  | 600 | nA |
| $\mathrm{I}_{\mathrm{B}}$ | Input Bias Current |  |  |  | $\pm 6$ | $\mu \mathrm{A}$ |
| $V_{C M}$ | Input Voltage Range (Positive) Input Voltage Range (Negative) |  | 3.5 |  | -3.5 | V |
| CMRR | Common Mode Rejection Ratio | $\mathrm{V}_{\text {CM }}= \pm 3.5 \mathrm{~V}$ | 72 |  |  | dB |

ELECTRACRL CHPRACTERISTMS $-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq 85^{\circ} \mathrm{C} . \mathrm{V}_{\mathrm{S}}= \pm 5 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=0 \mathrm{~V}$ unless otherwise noted (Note 8).

| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Minimum Supply Voltage |  |  | $\pm 2$ | V |
| PSRR | Power Supply Rejection Ratio | $\mathrm{V}_{S}= \pm 2 \mathrm{~V}$ to $\pm 5.5 \mathrm{~V}$ | 75 |  | dB |
| AVOL | Large-Signal Voltage Gain | $\begin{aligned} & V_{\text {OUT }}= \pm 3 V, R_{L}=500 \Omega \\ & V_{\text {OUT }}= \pm 3 V, R_{L}=100 \Omega \\ & \hline \end{aligned}$ | $\begin{aligned} & 0.8 \\ & 0.6 \end{aligned}$ |  | $\mathrm{V} / \mathrm{mV}$ $\mathrm{V} / \mathrm{mV}$ |
| $\mathrm{V}_{\text {OUT }}$ | Maximum Output Swing | $\begin{array}{\|l} \hline \mathrm{R}_{\mathrm{L}}=500 \Omega, 30 \mathrm{mV} \text { Overdrive } \\ \mathrm{R}_{\mathrm{L}}=100 \Omega, 30 \mathrm{mV} \text { Overdrive } \\ \hline \end{array}$ | $\begin{aligned} & \pm 3.60 \\ & \pm 3.15 \end{aligned}$ |  | V |
| IOUT | Maximum Output Current | $\mathrm{V}_{\text {OUT }}= \pm 3 \mathrm{~V}, 30 \mathrm{mV}$ Overdrive | $\pm 30$ |  | mA |
| ISC | Output Short-Circuit Current | $\mathrm{V}_{\text {OUT }}=0 \mathrm{~V}$, 1V Overdrive (Note 3) | $\pm 55$ |  | mA |
| SR | Slew Rate | $\mathrm{A}_{V}=-1$ (Note 5) | 350 |  | $\mathrm{V} / \mathrm{\mu S}$ |
| GBW | Gain Bandwidth Product | $\mathrm{f}=200 \mathrm{kHz}$ | 60 |  | MHz |
| ISHDN | $\overline{\text { SHDN }}$ Pin Current | $\begin{aligned} & \overline{\overline{S H D N}}>\mathrm{V}^{-}+2.0 \mathrm{~V}(0 n) \\ & \overline{\text { SHDN }}<\mathrm{V}^{-}+0.4 \mathrm{~V}(0 \mathrm{ff}) \end{aligned}$ | -200 | $\pm 2$ | $\mu \mathrm{A}$ $\mu \mathrm{A}$ |
| IS | Supply Current | $\begin{aligned} & \overline{\mathrm{SHDN}}>\mathrm{V}^{-}+2.0 \mathrm{~V}(0 \mathrm{On}) \\ & \overline{\text { SHDN }}<\mathrm{V}^{-}+0.4 \mathrm{~V}(0 \mathrm{ff}) \end{aligned}$ |  | $\begin{gathered} 5 \\ 200 \end{gathered}$ | mA $\mu \mathrm{A}$ |

$-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq 85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{S}}=5 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=2.5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}$ to 2.5 V unless otherwise noted (Note 8).

| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {OS }}$ | Input Offset Voltage | (Note 4) |  |  | 3.5 | mV |
| $\Delta \mathrm{V}_{0 \mathrm{~S}} / \Delta \mathrm{T}$ | Input Offset Voltage Drift | (Note 7) |  | 10 | 30 | $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ |
| OS | Input Offset Current |  |  |  | 600 | nA |
| IB | Input Bias Current |  |  |  | $\pm 6$ | $\mu \mathrm{A}$ |
| $\mathrm{V}_{\text {CM }}$ | Input Voltage Range (Positive) Input Voltage Range (Negative) |  | 3.5 |  | 1.5 | V |
| CMRR | Common Mode Rejection Ratio | $\mathrm{V}_{\text {CM }}=1.5 \mathrm{~V}$ to 3.5 V | 70 |  |  | dB |
| AVOL | Large-Signal Voltage Gain | $\begin{array}{\|l} \hline V_{\text {OUT }}=1.5 \mathrm{~V} \text { to } 3.5 \mathrm{~V}, R_{\mathrm{L}}=500 \Omega \\ \mathrm{~V}_{\text {OUT }}=2.0 \mathrm{~V} \text { to } 3.0 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=100 \Omega \\ \hline \end{array}$ | $\begin{aligned} & 0.6 \\ & 0.4 \end{aligned}$ |  |  | $\mathrm{V} / \mathrm{mV}$ <br> $\mathrm{V} / \mathrm{mV}$ |
| V OUT | Maximum Output Swing (Positive) | $\begin{aligned} & R_{L}=500 \Omega, 30 \mathrm{mV} \text { Overdrive } \\ & R_{L}=100 \Omega, 30 \mathrm{mV} \text { Overdrive } \end{aligned}$ | $\begin{aligned} & \hline 3.7 \\ & 3.5 \end{aligned}$ |  |  | V |
|  | Maximum Output Swing (Negative) | $\begin{array}{\|l} \hline R_{L}=500 \Omega, 30 \mathrm{mV} \text { Overdrive } \\ R_{L}=100 \Omega, 30 \mathrm{mV} \text { Overdrive } \\ \hline \end{array}$ |  |  | $\begin{aligned} & 1.3 \\ & 1.5 \end{aligned}$ | V |
| IOUT | Maximum Output Current | $\mathrm{V}_{\text {OUT }}=3.5 \mathrm{~V}$ or $1.5 \mathrm{~V}, 30 \mathrm{mV}$ Overdrive | $\pm 17$ |  |  | mA |
| $\underline{\text { SC }}$ | Output Short-Circuit Current | $\mathrm{V}_{\text {OUT }}=2.5 \mathrm{~V}$, 1V Overdrive (Note 3) | $\pm 40$ |  |  | mA |
| SR | Slew Rate | $\mathrm{A}_{V}=-1$ (Note 5) | 125 |  |  | $\mathrm{V} / \mathrm{\mu S}$ |
| GBW | Gain Bandwidth Product | $\mathrm{f}=200 \mathrm{kHz}$ | 50 |  |  | MHz |
| $\overline{\text { SHDN }}$ | $\overline{\text { SHDN }}$ Pin Current | $\begin{aligned} & \hline \overline{\mathrm{SHDN}}>\mathrm{V}^{-}+2.0 \mathrm{~V}(0 \mathrm{n}) \\ & \overline{\mathrm{SHDN}}<\mathrm{V}^{-}+0.4 \mathrm{~V}(0 \mathrm{ff}) \\ & \hline \end{aligned}$ | -100 |  | $\pm 2$ | $\mu \mathrm{A}$ $\mu \mathrm{A}$ |
| $\mathrm{I}_{S}$ | Supply Current | $\begin{aligned} & \overline{\mathrm{SHDN}}>\mathrm{V}^{-}+2.0 \mathrm{~V}(\mathrm{On}) \\ & \overline{\mathrm{SHDN}}<\mathrm{V}^{-}+0.4 \mathrm{~V}(0 \mathrm{ff}) \end{aligned}$ |  |  | $\begin{gathered} \hline 5 \\ 100 \end{gathered}$ | mA $\mu \mathrm{A}$ |

Note 1: Absolute Maximum Ratings are those values beyond which the life of the device may be impaired.
Note 2: Differential inputs of $\pm 3 \mathrm{~V}$ are appropriate for transient operation only, such as during slewing. Large sustained differential inputs can cause excessive power dissipation and may damage the part.
Note 3: A heat sink may be required to keep the junction temperature below absolute maximum when the output is shorted indefinitely.
Note 4: Input offset voltage is pulse tested and is exclusive of warm-up drift.
Note 5: Slew rate is measured between $\pm 2 \mathrm{~V}$ on the output with $\pm 3 \mathrm{~V}$ input for $\pm 5 \mathrm{~V}$ supplies and $2 \mathrm{~V}_{\text {P-p }}$ on the output with a $3 \mathrm{~V}_{\text {P-p }}$ input for single 5 V supplies.

Note 6: Full power bandwidth is calculated from the slew rate: FPBW $=S R / 2 \pi V_{p}$.
Note 7: This parameter is not $100 \%$ tested.
Note 8: The LT1812C is guaranteed to meet specified performance from $0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$. The LT1812C is designed, characterized and expected to meet specified performance from $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ but is not tested or QA sampled at these temperatures. The LT1812I is guaranteed to meet specified performance from $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$.
Note 9: $\theta_{\mathrm{JA}}$ is specified for a $2500 \mathrm{~mm}^{2}$ board covered with 2 oz copper on both sides. Thermal resistance varies, depending upon the amount of PC board metal attached to the device. For this package in particular, power is dissipated primarily through Pin 4 , which should therefore, have a good thermal connection to a copper plane.

## LT1812

## TYPICAL PGRFORmANCE CHARACTERISTICS



## TYPICAL PERFORmARCE CHARACTERISTICS



## TYPICAL PGRFORMANCE CHARACTERISTICS



1812 G19


1812 G22


Slew Rate vs Temperature


Slew Rate vs Supply Voltage


1812633

Total Harmonic Distortion + Noise vs Frequency


Common Mode Rejection Ratio vs Frequency


1812 G21
Slew Rate vs Input Level


Undistorted Output Swing vs Frequency


## TYPICAL PERFORmANCE CHARACTERISTICS



1812 G28
Small-Signal Transient,
$A_{V}=-1$


Large-Signal Transient,
$A_{V}=-1$


Differential Gain and Phase
vs Supply Voltage


Small-Signal Transient,
$A_{V}=1$


Large-Signal Transient,
$A_{V}=1$


Capacitive Load Handling


Small-Signal Transient,
$A_{V}=1, C_{L}=1000 \mathrm{pF}$


Large-Signal Transient,
$A_{V}=1, C_{L}=1000 \mathrm{pF}$


## APPLICATIONS INFORMATION

Layout and Passive Components

The LT1812 amplifier is more tolerant of less than ideal layouts than other high speed amplifiers. For maximum performance (for example, fast settling) use a ground plane, short lead lengths and RF-quality bypass capacitors ( $0.01 \mu \mathrm{~F}$ to $0.1 \mu \mathrm{~F}$ ). For high drive current applications, use low ESR bypass capacitors ( $1 \mu \mathrm{~F}$ to $10 \mu \mathrm{~F}$ tantalum).

The parallel combination of the feedback resistor and gain setting resistor on the inverting input combine with the input capacitance to form a pole that can cause peaking or even oscillations. If feedback resistors greater than $2 k$ are used, a parallel capacitor of value

$$
\mathrm{C}_{F}>\mathrm{R}_{G} \cdot \mathrm{C}_{I N} / R_{F}
$$

should be used to cancel the input pole and optimize dynamic performance. For applications where the DC noise gain is 1 and a large feedback resistor is used, $\mathrm{C}_{\mathrm{F}}$ should be greater than or equal to $\mathrm{C}_{\mathrm{IN}}$. An example would be an I-to-V converter.

## Input Considerations

Each of the LT1812 amplifier inputs is the base of an NPN and PNP transistor whose base currents are of opposite polarity and provide first-order bias current cancellation. Because of variation in the matching of NPN and PNP beta, the polarity of the input bias current can be positive or negative. The offset current does not depend on beta matching and is well controlled. The use of balanced source resistance at each input is recommended for applications where DC accuracy must be maximized. The inputs can withstand differential input voltages of up to 3 V without damage and need no clamping or source resistance for protection.
The device should not be used as a comparator because with sustained differential inputs, excessive power dissipation may result.

## Capacitive Loading

The LT1812 is stable with a 1000pF capacitive load, which is outstanding for a 100 MHz amplifier. This is accomplished by sensing the load induced output pole and adding compensation at the amplifier gain node. As the
capacitive load increases, both the bandwidth and phase margin decrease so there will be peaking in the frequency domain and in the transient response. Coaxial cable can be driven directly, but for best pulse fidelity, a resistor of value equal to the characteristic impedance of the cable (i.e., $75 \Omega$ ) should be placed in series with the output. The other end of the cable should be terminated with the same value resistor to ground.

## Slew Rate

The slew rate is proportional to the differential input voltage. Highest slew rates are therefore seen in the lowest gain configurations. For example, a 5 V output step in a gain of 10 has a 0.5 V input step, whereas in unity gain there is a 5 V input step. The LT1812 is tested for slew rate in a gain of -1 . Lower slew rates occur in higher gain configurations.

## Shutdown

The LT1812 has a shutdown pin ( $\overline{\mathrm{SHDN}}$, Pin 8) for conserving power. When this pin is open or biased at least 2 V above the negative supply, the part operates normally. When pulled down to $\mathrm{V}^{-}$, the supply current drops to about $50 \mu \mathrm{~A}$. Typically, the turn-off delay is $1 \mu \mathrm{~s}$ and the turn-on delay $0.5 \mu \mathrm{~s}$. The current out of the SHDN pin is also typically $50 \mu \mathrm{~A}$. In shutdown mode, the amplifier output is not isolated from the inputs, so the LT1812 shutdown feature cannot be used for multiplexing applications. The $50 \mu \mathrm{~A}$ typical shutdown current is exclusive of any output (load) current. In order to prevent load current (and maximize the power savings), either the load needs to be disconnected, or the input signal needs to be OV. Even in shutdown mode, the LT1812 can still drive significant current into a load. For example, in an $A_{V}=1$ configuration, when driven with a 1V DC input, the LT1812 drives 2 mA into a $100 \Omega$ load. It takes about $500 \mu \mathrm{~s}$ for the load current to reach this value.

## Power Dissipation

The LT1812 combines high speed and large output drive in a small package. It is possible to exceed the maximum junction temperature under certain conditions. Maximum

## APPLICATIONS INFORMATION

junction temperature $\left(T_{J}\right)$ is calculated from the ambient temperature $\left(\mathrm{T}_{\mathrm{A}}\right)$ and power dissipation $\left(\mathrm{P}_{\mathrm{D}}\right)$ as follows:

LT1812CS8: $T_{J}=T_{A}+\left(P_{D} \bullet 80^{\circ} \mathrm{C} / \mathrm{W}\right)$ (Note 9)
Power dissipation is composed of two parts. The first is due to the quiescent supply current and the second is due to on-chip dissipation caused by the load current. The worst-case load induced power occurs when the output voltage is at $1 / 2$ of either supply voltage (or the maximum swing if less than $1 / 2$ supply voltage). Therefore $\mathrm{P}_{\mathrm{DMAX}}$ is:

$$
\begin{aligned}
& P_{\text {DMAX }}=\left(\mathrm{V}^{+}-\mathrm{V}^{-}\right)\left(\mathrm{I}_{\text {SMAX }}\right)+\left(\mathrm{V}^{+} / 2\right)^{2} / \mathrm{R}_{\mathrm{L}} \text { or } \\
& \mathrm{P}_{\text {DMAX }}=\left(\mathrm{V}^{+}-\mathrm{V}^{-}\right)\left(\mathrm{I}_{\text {SMAX }}\right)+\left(\mathrm{V}^{+}-\mathrm{V}_{\text {OMAX }}\right)\left(\mathrm{V}_{\text {OMAX }} / \mathrm{R}_{\mathrm{L}}\right)
\end{aligned}
$$

Example: LT1812CS8 at $70^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{S}}= \pm 5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=100 \Omega$

$$
\begin{aligned}
& P_{\text {DMAX }}=(10 \mathrm{~V})(4.5 \mathrm{~mA})+(2.5 \mathrm{~V})^{2} / 100 \Omega=108 \mathrm{~mW} \\
& \mathrm{~T}_{\text {JMAX }}=70^{\circ} \mathrm{C}+(108 \mathrm{~mW})\left(80^{\circ} \mathrm{C} / \mathrm{W}\right)=79^{\circ} \mathrm{C}
\end{aligned}
$$

## Circuit Operation

The LT1812 circuit topology is a true voltage feedback amplifier that has the slewing behavior of a current feedback amplifier. The operation of the circuit can be understood by referring to the Simplified Schematic. The inputs are buffered by complementary NPN and PNP emitter followers that drive a $300 \Omega$ resistor. The input voltage
appears across the resistor generating currents that are mirrored into the high impedance node. Complementary followers form an output stage that buffers the gain node from the load. The bandwidth is set by the input resistor and the capacitance on the high impedance node. The slew rate is determined by the current available to charge the gain node capacitance. This current is the differential input voltage divided by R1, so the slew rate is proportional to the input. Highest slew rates are therefore seen in the lowest gain configurations. The RC network across the output stage is bootstrapped when the amplifier is driving a light or moderate load and has no effect under normal operation. When driving capacitive loads (or a low value resistive load) the network is incompletely bootstrapped and adds to the compensation at the high impedance node. The added capacitance slows down the amplifier which improves the phase margin by moving the unitygain cross away from the pole formed by the output impedance and the capacitive load. The zero created by the RC combination adds phase to ensure that the total phase lag does not exceed 180 degrees (zero phase margin) and the amplifier remains stable. In this way, the LT1812 is stable with up to 1000 pF capacitive loads in unity gain, and even higher capacitive loads in higher closed-loop gain configurations.

## SImPLIFIED SCHEMATIC



## LT1812

## TYPICAL APPLICATION

Single 5V Supply 10MS/s 12-Bit ADC Buffer


## PACKAGE DESCRIPTION

S8 Package
8-Lead Plastic Small Outline (Narrow 0.150)
(LTC DWG \# 05-08-1610)


## RELATGD PARTS

| PART NUMBER | DESCRIPTION | COMMENTS |
| :---: | :---: | :---: |
| LT1360/LT1361/LT1362 | Single/Dual/Quad 50MHz, 800V/ $\mu$ s, C-Load ${ }^{\text {TM }}$ Amplifiers | 4mA Supply Current, 1mV Max $\mathrm{V}_{\text {OS }}, 1 \mu \mathrm{~A} \mathrm{Max} \mathrm{I}_{\mathrm{B}}$ |
| LT1363/LT1364/LT1365 | Single/Dual/Quad 70MHz, 1000V/ $/$ S C-Load Amplifiers | 50 mA Output Current, 1.5 mV Max $\mathrm{V}_{\text {OS }}, 2 \mu \mathrm{~A} \mathrm{Max} \mathrm{I}_{\text {B }}$ |
| LT1395/LT1396/LT1397 | Single/Dual/Quad 400MHz Current Feedback Amplifiers | 4.6 mA Supply Current, $800 \mathrm{~V} / \mathrm{\mu s}, 80 \mathrm{~mA}$ Output Current |
| LT1398/LT1399 | Dual/Triple 300MHz Current Feedback Amplifiers | 4.5 mA Supply Current, 80mA Output Current, Shutdown |
| LT1813 | Dual 3mA, 100MHz, 750V/ $\mathrm{\mu s}$ Operational Amplifier | Dual Version of the LT1812 |

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